

# Identifying the optimal sampling design for the inventorying and monitoring of medium- and large-sized mammals

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## Abstract:

This study aims to identify optimal sampling designs for the inventory and monitoring of medium- and large-sized mammals, considering different biodiversity dimensions (taxonomic, functional, and phylogenetic) in the Southern Brazilian Amazon. We established three line transects each 3 km long, and three camera trap grids, each with six cameras, totaling 176 kilometers walked and 4,914 camera trap-days. We defined fixed and variable costs associated with each method. We sought to identify the sampling arrangement that yielded the highest possible  $\alpha$ -diversity at the lowest possible cost (i.e., inventory efficiency), and the combination of methods that minimized bias in recording  $\beta$ -diversity while also minimizing costs (i.e., monitoring efficiency). Camera traps detected 26 species, of which 16 were exclusive to this method. Line transects resulted in detection of 16 species, six of which were exclusive (all arboreal). It was generally not possible to identify a single sampling scheme that yielded higher diversity or lower bias at lower costs. However, it was clear that adding line transect sampling units increased costs without improving diversity or bias results. Then, for the inventory of functional and phylogenetic diversity and for monitoring taxonomic, functional, and phylogenetic diversity, the optimal sampling design involves the exclusive use of camera traps. For a taxonomic diversity inventory the optimal sampling scheme requires a combination of camera traps and line transects. We did not sweep the transects or search for tracks and other signs in our line transect surveys, which reduced the method's effectiveness in detecting some species. The superior cost-effectiveness of camera traps can be related to improvements in camera trap technology and reductions in their cost, although given their lower efficiency to detect arboreal species, including some effort in line transects may be necessary.

**Keywords:** Amazon, Camera traps, Functional diversity, line-transects, Neotropical mammals, Phylogenetic diversity.

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**Running title:** Optimal sampling design for mammals

### Abstract

This study aims to identify optimal sampling designs for the inventory and monitoring of medium- and large-sized mammals, considering different biodiversity dimensions (taxonomic, functional, and phylogenetic) in the Southern Brazilian Amazon. We established three line transects each 3 km long, and three camera trap grids, each with six cameras, totalling 176 kilometers walked and 4,914 camera trap-days. We defined fixed and variable costs associated with each method. We sought to identify the sampling arrangement that yielded the highest possible  $\alpha$ -diversity at the lowest possible cost (i.e., inventory efficiency), and the combination of methods that minimized bias in recording  $\beta$ -diversity while also minimizing costs (i.e., monitoring efficiency). Camera traps detected 26 species, of which 16 were exclusive to this method. Line transects resulted in detection of 16 species, six of which were exclusive (all arboreal). It was generally not possible to identify a single sampling scheme that yielded higher diversity or lower bias at lower costs. However, it was clear that adding line transect sampling units increased costs without improving diversity or bias results. Then, for the inventory of functional and phylogenetic diversity and for monitoring taxonomic, functional, and phylogenetic diversity, the optimal sampling design involves the exclusive use of camera traps. For a taxonomic diversity inventory the optimal sampling

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37 diversity, Phylogenetic diversity

## 38 INTRODUCTION

39 Faunal inventories aim to record the diversity of a given location with the highest level of  
40 completeness as possible, while faunal monitoring is conducted to detect changes in  
41 community composition over time (Cardoso et al. 2024a). Inventories are essential for  
42 understanding local biodiversity and identifying areas of higher or lower species richness,  
43 thus providing a foundation for conservation decision-making (Silva-Dias et al. 2019). On the  
44 other hand, monitoring allows researchers to track the effects of environmental changes or  
45 interventions on biodiversity. In this context, efficient inventories seek to maximize recorded  
46  $\alpha$ -diversity at the lowest possible cost (Cardoso et al. 2024a, Burt et al. 2021, Carvalho et al.  
47 2016, Garden et al. 2007, Gaidet-Drapier et al. 2006). Conversely, monitoring efforts require  
48 comparing community composition over different time periods (i.e.,  $\beta$ -diversity), and  
49 therefore aim to minimize the discrepancy between true and sampled  $\beta$ -diversity (i.e.,  
50 minimize bias in recording  $\beta$ -diversity – Cardoso et al. 2024a). True  $\beta$ -diversity represents  
51 differences in assemblage composition among sites estimated by pooling data from all  
52 sampling units, i.e. the  $\beta$ -diversity obtained under intensive sampling. Bias is calculated as the  
53 difference between estimates obtained from subsets of sampling units and those derived from  
54 the complete dataset (Cardoso et al. 2024a).

55 Although inventories and monitoring have distinct objectives, they are often carried out using  
56 similar methods for each taxonomic group (e.g., Welbourne et al. 2015, Garden et al. 2007).  
57 The existence of numerous methods used in faunal inventories and monitoring highlights the  
58 need to understand the limitations and advantages of each, supporting the selection of the  
59 most appropriate approaches for each situation (Burt et al. 2021, Carvalho et al. 2016, Gaidet-

61 Drapier et al. 2006). The primary methods employed in the inventory and monitoring of  
62 medium- and large-sized mammals include camera trapping, line transect surveys, and the  
63 identification of tracks and other signs (e.g., scratches, vocalizations, burrows, hair, odors –  
64 Meek et al. 2012; Cullen & Rudran 2006). Camera trapping involves placing cameras at  
65 predefined locations to record the species present and gathering information on their spatial  
66 distribution and relative abundance (Kéry 2011). Line transect surveys involve walking along  
67 predefined paths and recording sightings, allowing the assessment of species distribution  
68 along the surveyed or monitored area (Buckland et al. 2015). This method also allows for the  
69 concurrent recording of tracks and other mammalian signs.

70 The characteristics of camera traps and line transects make each more suited for detecting  
71 species with different traits. While camera traps are more effective for detecting elusive, rare,  
72 and nocturnal animals (Benchimol 2016), line transects are more advantageous for sampling  
73 arboreal and diurnal fauna (Wix & Reich 2019, Carvalho et al. 2016, Roberts et al. 2016,  
74 Trolle et al. 2008). Thus, it is common for both methods to be used complementarily to  
75 improve species detection (Ponce-Martins et al. 2022, Moore et al. 2020). However, the  
76 simultaneous use of both methods often depends on the available budget and time for  
77 fieldwork. It is important to consider that camera traps remain relatively expensive due to  
78 their initial acquisition costs and potentially high maintenance and logistical expenses (Djekda  
79 et al. 2020, Lyra-Jorge et al. 2008, Silveira et al. 2003). Line transects, in turn, require more  
80 field effort, which can represent a significant cost depending on the number of days in the  
81 field (Carvalho et al. 2016). Therefore, to define an optimal allocation of effort between the  
82 two methods in inventories or monitoring of mammals, it is necessary to balance species  
83 detectability and the associated costs of each method.

84 Biological diversity can be assessed through multiple dimensions, including taxonomic,  
85 functional, and phylogenetic diversity (Chao et al. 2014). Taxonomic diversity is the most  
86 commonly used dimension, but it disregards ecological and evolutionary differences among  
87 species (Cardoso et al. 2024b; Chao et al. 2014, Purschke et al. 2013). Conversely, functional  
88 and phylogenetic diversity weight species according to their ecological traits and evolutionary  
89 lineages, respectively (Cardoso et al. 2024b, Chao et al. 2014). Given that camera traps and  
90 line transects differ in the species profile they tend to detect (Carvalho et al. 2016), these  
91 differences are expected to influence functional and phylogenetic diversity outcomes. For  
92 example, the concentration of line transect records on diurnal animals, and of camera trap

94 records on terrestrial species (Moore et al. 2020, Carvalho et al. 2016) limits the functional  
95 diversity captured by these methods. Additionally, Neotropical primates—a speciose lineage  
96 of mammals—are predominantly arboreal (Paglia et al. 2012), which restricts the  
97 phylogenetic diversity captured by camera traps at ground level, as these devices are generally  
98 inefficient at detecting arboreal species. Thus, the optimal allocation of mammal sampling  
99 methods may vary depending on the assessed biodiversity dimension.

100 We sought to identify optimal sampling designs for the inventory and monitoring of medium-  
101 and large-sized mammals, considering different biodiversity dimensions (taxonomic,  
102 functional, and phylogenetic). The ultimate goal is to inform future research and improve  
103 sampling efficiency, i.e., maximize the number of species detected or minimize the bias in  
104 comparing species composition, while minimizing costs.

## 105 MATERIALS AND METHODS

### 106 Study Area

107 The study was conducted in the area of the Rondon II Hydroelectric Power Plant (Rondon II  
108 HPP), located in the state of Rondônia, in the southern Brazilian Amazon. The region is  
109 predominantly covered by Seasonal Semideciduous Forest and lies within the transition zone  
110 between the Amazon and Cerrado biomes, which influences its fauna and flora (Radam Brasil  
111 1978). The Rondon II reservoir spans 4,930 hectares and is surrounded by approximately  
112 11,000 hectares of forest (Rondônia 2002), contiguous with other forested areas in the  
113 surrounding landscape (Fig. 1). In well-preserved areas, the forest canopy can exceed 20  
114 meters in height and includes a well-developed understory (Mattos et al. 2023). The region's  
115 soils are classified as hydromorphic quartzarenic with sandy texture and low relief (IBGE  
116 2006). According to Köppen's classification, the local climate is Aw (tropical wet and dry  
117 climate with a dry winter – Kottek et al. 2006, IBGE 2002). The dry season lasts  
118 approximately three months, from June to August, while the rainy season generally spans  
119 from September to May (IBGE 2002). Average monthly precipitation during the driest  
120 months is below 50 mm, with total annual precipitation ranging from 1,400 to 2,600 mm.  
121 Annual mean temperatures vary from 21 to 37°C (Rondônia 2002).

123 **Data Collection**124 *Line Transects*125 We established three line transects, each with 3 Km, within the study area (Fig. 1). The  
126 transects were established in November 2017 to enable fauna monitoring at the Rondon II  
127 HPP, and their number and length were defined according to operational limitations at the  
128 locations where they were established and by the size constraints of the study site. Transects  
129 were cleared once or twice a year to remove shrubs growing along the trails and fallen  
130 branches and trees. However, the trails were not swept due to the high cost of this activity.131 Transects were surveyed during 4-day field campaigns conducted two to five times per year  
132 between July 2019 and March 2025. Surveys were carried out by two observers walking at a  
133 constant speed of 1.5 km/h, searching for direct sightings of mammals. From 2019 to 2023,  
134 each transect was walked only once per field campaign. In the five campaigns conducted in  
135 2024 and 2025, transects were walked between one and three times per campaign. In these  
136 cases, once a transect was sampled, it was not surveyed again for at least 48 hours to allow for  
137 the natural repositioning of wildlife and to ensure independence of records across different  
138 days on the same transect. This resulted in a total sampling effort of 222 kilometers walked.139 *Camera Traps*140 Around each transect, we installed a rectangular grid (1 x 3 km) of camera traps (Tasco Low  
141 Glow 12MP Trail Camera, with infrared flash and a 1-second trigger speed), with six camera  
142 traps placed 1 km apart and approximately 500 meters from the trail (three on each side – Fig.  
143 1). The distance between camera traps was chosen to ensure the independence of recorded  
144 data (e.g., Brandão et al. 2025). Cameras were mounted on tree trunks approximately 40  
145 centimeters above the ground, in locations selected to maximize mammal detection, such as  
146 along natural animal paths. Cameras were programmed to operate 24 hours per day, and  
147 records of the same species at the same camera were considered independent if they occurred  
148 more than one hour apart (Tobler et al. 2008). Across the 18 camera trap sites, we obtained a  
149 sampling effort of 4,914 trap-days over an eight-month sampling period (from May 2024 to  
150 February 2025). However, a smaller effort (4,320 trap-days) was used in the analysis due to  
151 unbalanced sampling between points.152 Transects were surveyed over a longer period (6 years) than camera traps (8 months), which  
153 may be a problem if the mammal assemblage varied during this time. To account for this  
154 temporal mismatch, we tested whether the number of species recorded per transect differed

156 among the six years of transect surveys. Since we did not find evidence of significant changes  
157 in the assemblage (Permutational ANOVA:  $F=2.488$ ;  $p=0.078$ ), this mismatch does not  
158 represent a problem for our analyses.

159 *Cost Definition for Methods*

160 We categorized the costs associated with each method into fixed and variable costs (Tab. 1,  
161 e.g., Lyra-Jorge et al. 2008). Fixed costs were defined as those that do not vary with temporal  
162 replication of sampling (e.g., equipment purchase, trail establishment, etc.). Variable costs  
163 vary proportionally with the number of sampling units used in the study (e.g., transportation  
164 within the study area, researcher accommodation and meals, researcher per diems, vehicle  
165 rental, and fuel – Tab. 1). Costs were initially estimated in Brazilian reais (R\$) and  
166 subsequently converted to U.S. dollars (US\$) using an exchange rate of R\$1.00 = US\$5.97 (as  
167 of March 17, 2025).

168 **Statistical Analyses**

169 In this study, to identify the optimal sampling design for inventories, we used the *optim.alpha*  
170 function (Cardoso et al. 2024a) of the package ‘BAT’ (Cardoso et al. 2015), which seeks to  
171 identify the sampling arrangement that yields the highest possible  $\alpha$ -diversity at the lowest  
172 possible cost. According to the method characteristics, the sampling units of the different  
173 methods do not need to be equivalent. The size of the sampling unit represents the size of the  
174 increment in cost and diversity/bias when a sampling unit is added to the sample (Cardoso et  
175 al. 2015). Therefore, sampling units should be relatively small to allow a fine-grained  
176 evaluation, while still being meaningful, i.e., representing what can typically be achieved in a  
177 field campaign. We defined sampling units as 90 camera trap-days, i.e., 30 days of sampling  
178 in a half-grid (3 camera traps), and 18 kilometers walked on transects, i.e., one 4-day  
179 sampling campaign across the three transects. Although replication of camera traps can be  
180 achieved either by increasing the number of devices or by extending their deployment time in  
181 the field, in this study we considered only temporal replication. Thus, fixed costs were based  
182 on the purchase value of three camera traps, regardless of the number of sampling units.

183 To identify the optimal design for mammal monitoring, we used the *optim.beta* function  
184 (Cardoso et al. 2024a), which identifies the combination of methods that minimizes bias in  
185 recording  $\beta$ -diversity while also minimizing costs. Although monitoring aims to assess

187 changes in the community over time, the evaluation of the sampling effort that minimizes bias  
188 in differences between surveys can be carried out either spatially or temporally. Therefore, for  
189 this analysis,  $\beta$ -diversity was assessed as the Jaccard distance between the three transects and  
190 between the three camera trap grids, and we considered each sampling unit as one transect  
191 surveyed four times (i.e., 12 km), and 30 days of sampling within a grid of six camera traps  
192 (i.e., 180 camera trap-days). Note that the sampling units differ from those used in the  
193 inventory analysis, because in the monitoring analyses we need to assess beta diversity  
194 between transects or camera-trap grids. Both the inventory and monitoring analyses were  
195 conducted using taxonomic, functional, and phylogenetic diversity.

196 Optimal sampling arrangements were identified using plots that relate diversity (inventory) or  
197 1 – bias (monitoring) to the cost associated with each sampling arrangement. Each point in  
198 these plots represents a combination of sampling units from the different methods. To identify  
199 the number of sampling units from each method represented by each point, we used the  
200 function ‘identify’. Identifying the optimal design is more straightforward when there is a  
201 clear inflection point beyond which increasing sampling costs does not lead to a substantial  
202 increase in diversity or 1 – bias. However, when diversity or 1 – bias increases gradually with  
203 sampling cost, defining an optimal design becomes more subjective.

204 To obtain the optimal sampling design for inventories and monitoring of medium- and large-  
205 sized mammals based on phylogenetic diversity, we generated a consensus phylogenetic tree  
206 of the species recorded in this study using the VertLife.org database (Upham et al. 2019). For  
207 the functional dimension, we used functional data related to diet (proportion of diet consisting  
208 of invertebrates, fish, vertebrates, carrion, fruits+seeds, nectar, and leaves), activity period  
209 (whether the animal is active during the day, night, or twilight), and body size (log-  
210 transformed). These data were obtained from Wilman et al. (2014). Based on these data, we  
211 created a distance matrix between species using the *gawdis* function of the package ‘gawdis’  
212 (de Bello et al. 2021), specifying that the diet and activity period variables were grouped. We  
213 then built a functional tree based on the resulting distance matrix using the *tree.build* function  
214 of the package ‘BAT’ (Cardoso et al. 2015). All the analyses were performed in the software  
215 R (R Core Team 2025).

**RESULTS**

Considering both methods used, we recorded 32 species of medium- and large-sized mammals in the study area (Tab. 2). Camera traps detected 26 species, of which 16 were exclusive to this method. Among the species recorded exclusively by camera traps, most were terrestrial, but scansorial species (such as the South American Coati and the Brazilian Squirrel) and arboreal species (e.g., the Black-tailed Marmoset) were also detected (Tab. 2). In contrast, the line transect method detected 16 species, 6 of which were exclusive to this method—five primates species, and the Brazilian Porcupine (Tab. 2).

Regarding the taxonomic diversity inventory, the graph shows a sequence of ascending curves from left to right (Fig. 2). On the far left of the graph, the curve that stands out most includes only sampling units composed of camera traps. The addition of line transect sampling units shifts the curves to the right, increasing the cost and correspondingly increasing the resulting diversity. There is a gradual increase in diversity with sampling cost, such that within the sampling limits of this study, it is not possible to objectively define an optimal sampling design for the inventory of taxonomic diversity of medium- and large-sized mammals.

The same initial ascending trend is observed for functional diversity inventory, with the curve on the far left composed of camera-trap-only sampling units. Adding line transect units again shifts the curve to the right, indicating increased cost. However, unlike taxonomic diversity, the corresponding increase in functional diversity is comparatively small. Thus, the optimal sampling design for functional diversity inventory involves using only camera traps, although the decision regarding the number of cameras remains somewhat subjective. The curve stabilizes, indicating that beyond a certain number of camera trap units, the cost increases faster than the gain in diversity. Therefore, the optimal number of sampling units lies between 720 and 3600 camera trap-days, at a cost ranging from US\$ 6,751.01 to US\$ 32,714.85 (Fig. 2).

For phylogenetic diversity, the pattern is similar to that observed for functional diversity. The graph also shows an ascending curve on the left composed of sampling units using only camera traps. This curve stabilizes more quickly, suggesting that the optimal sampling design for the inventory of phylogenetic diversity requires less sampling effort and lower cost: between 450 and 1440 camera trap-days, with a corresponding cost ranging from US\$ 4,316.90 to US\$ 13,241.97 (Fig. 2).

249 Regarding monitoring, for all biodiversity dimensions (i.e., taxonomic, functional, and  
250 phylogenetic), we observed a sequence of points on the left side of the graph that show an  
251 increase in the 1 - bias ratio as the number of camera traps increases, without including any  
252 transect sampling units. Adding transect units shifts the curve to the right—i.e., it increases  
253 cost—with only a minor improvement in the 1 - bias ratio. Therefore, the optimal monitoring  
254 design can also be defined as one relying solely on camera traps, although the precise number  
255 of cameras used remains a subjective choice, considering that increasing the number of  
256 cameras reduces bias. The costs associated with the optimal sampling schemes for monitoring  
257 are similar between taxonomic, functional, and phylogenetic diversities (Fig. 2). Furthermore,  
258 the monitoring costs are lower than those required for inventorying (Fig. 2).

## 259 DISCUSSION

260 We showed that for the inventory of functional and phylogenetic diversity of medium- and  
261 large-sized mammals and for monitoring taxonomic, functional, and phylogenetic diversity,  
262 the optimal sampling design involves the exclusive use of camera traps. Only in the case of  
263 taxonomic diversity inventory did the optimal sampling scheme require a combination of  
264 camera traps and line transects.

265 The superior cost-effectiveness of camera traps in recording mammal species can be  
266 attributed to several factors. First, the cost of camera traps has declined over the years, while  
267 the quality of the devices has improved in terms of sensor sensitivity, trigger speed, and  
268 image resolution (Rovero et al. 2013, Swann et al. 2011). This has led to lower fixed costs  
269 and increased efficiency in mammal detection (Palencia et al. 2022, Rovero et al. 2013,  
270 Swann et al. 2011). Furthermore, the extended battery life and high-capacity memory cards  
271 reduce variable costs by decreasing the need for frequent field visits (Swann et al. 2011). As a  
272 result, both fixed and variable costs of camera trapping have become lower than those of line  
273 transects, as our results showed. It is also worth noting that the camera trap model used in this  
274 study (Tasco Low Glow 12MP Trail Camera) had a relatively low cost (US\$ 50.36 per unit,  
275 including import taxes) compared to other models, which may have further favored camera  
276 traps in our cost-effectiveness analysis.

Our results contrast with those of previous studies conducted in Neotropical ecosystems similar to our study area. For example, studies have found greater efficiency for line transects (Silveira et al. 2003), similar cost-effectiveness between camera traps and line transects (Carvalho et al. 2016), or the need for a combination of methods (Munari et al. 2011). Several factors may explain these differences. Notably, Silveira et al. (2003) and Munari et al. (2011) did not incorporate sampling costs into their evaluations. Carvalho et al. (2016) was carried out on already established transects and did not consider the cost of establishing them, which can be substantial when trails are not already present in the study area. Additionally, improvements in camera trap technology and reductions in their cost since those studies were published help explain the divergent findings. Finally, we did not sweep the transects or include the search for tracks and other signs in our line transect surveys, which reduced the method's effectiveness in detecting some species. In fact, sign detection is essential for increasing the effectiveness of line transect surveys (Carvalho et al. 2016, Silveira et al. 2003) and including sign detection in our analyses could have qualitatively altered the results. On the other hand, the ongoing development of camera trap technology and continued cost reductions are likely to favor this method increasingly. This is supported by more recent studies, such as Djekda et al. (2020), which also found camera traps to be the most cost-effective method for sampling African mammals. Similarly, there has been ongoing development in the use of drones for species inventorying (Larsen et al. 2023). Such developments may expand their applications and reduce costs, potentially leading to improved cost-effectiveness in the future (Burke et al. 2019). Importantly, our results indicate greater cost-effectiveness of camera traps only for inventorying or monitoring purposes. The use of camera traps in studies with different objectives, such as estimating species density, is expected to result in substantially different cost-effectiveness trade-offs (e.g. Delisle et al. 2023).

The result for the taxonomic diversity inventory was the only one that indicated the need to combine line transects with camera traps. This finding is associated with the fact that six species—all arboreal—were recorded exclusively by line transects, as also demonstrated by other studies in the Neotropical region (e.g., Moore et al. 2020, Carvalho et al. 2016). Thus, the most favorable strategy for species inventories is to rely primarily on camera traps, while allocating some sampling effort to line transects to record arboreal species.

310 Taxonomic diversity is often the focus of mammal biodiversity studies (Xavier et al. 2023).  
311 However, we showed that functional and phylogenetic diversity can be assessed at a lower  
312 cost, due to the sharing of functional traits among species and because certain lineages include  
313 species that are more easily detected than others. Indeed, camera traps were able to detect  
314 some arboreal species—such as the Black-capped Capuchin Monkey, Golden-backed Squirrel  
315 Monkey, and Black-tailed Marmoset—and recorded species from all mammalian orders and  
316 15 out of the 18 families identified in this study. Therefore, despite their lower effectiveness  
317 in detecting primates and other arboreal mammals (Srbek-Araujo & Chiarello 2005), camera  
318 traps can still record these animals, supporting their high efficiency in functional and  
319 phylogenetic diversity inventories.

320 We also found that monitoring medium- and large-sized mammals using only camera traps  
321 provides the best cost-effectiveness. In contrast, Munari et al. (2011) recommended  
322 combining multiple methods to monitor Amazonian mammals. Once again, it is important to  
323 highlight that camera traps, when installed at ground level, are less effective at detecting  
324 arboreal species (Srbek-Araujo and Chiarello 2005; Carvalho et al. 2016). Therefore, if the  
325 monitoring objective targets arboreal mammals, it is necessary to include some effort in line  
326 transects. However, if the goal is to assess changes in the composition of medium- and large-  
327 sized mammal communities more broadly and with minimal cost, then relying exclusively on  
328 camera traps is the most appropriate approach. Another possible strategy is installing camera  
329 traps in the canopy. This approach is more challenging than installing camera traps at ground  
330 level, due to undesired triggers and higher installation costs. Although recent advances have  
331 reduced these problems, camera traps in the canopy still seem to require higher costs per  
332 species recorded than those at ground level (Goebel et al. 2025). A formal comparison of the  
333 costs of using canopy camera traps and line transects is necessary to determine which method  
334 is more cost-effective.

335 Monitoring costs were lower than inventory costs, which is both expected and necessary,  
336 given the requirement for temporal replication in monitoring (Cardoso et al. 2024a). Sampling  
337 with up to 2880 camera trap-days (i.e., the total effort employed in our monitoring analysis)  
338 appears sufficient to detect temporal variation in large mammal community composition.  
339 While this sampling effort may require an important initial investment, the low cost of  
340 temporal replication with camera traps makes it feasible for long-term studies (Djekda et al.  
341 2020, Silveira et al. 2003).

Finally, our findings reflect, to some extent, the biodiversity characteristics of our study area. With eight primate species and the Brazilian Porcupine, the study site is particularly rich in arboreal mammals, favouring sampling designs that incorporate line transects. In areas with fewer arboreal species, inventories and monitoring may be even more efficiently conducted using only camera traps. On the other hand, including line transects may be advisable even for monitoring or for functional and phylogenetic diversity inventories in areas potentially harbouring a greater number of arboreal species. Besides the number of arboreal species, the balance between camera traps and line transects for mammal inventory and monitoring may also depend on the site's vegetation structure. For example, in open environments, the effectiveness of line transects may increase due to greater visibility. This increased visibility does not benefit camera traps, which typically detect animals only within a limited range (e.g., up to 30 meters). Thus, conducting similar analyses in regions with high arboreal mammal diversity is crucial to better elucidate the potential role of line transects in mammal inventory and monitoring under different ecological contexts.

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510  
511 **Table 1** - Values in USD representing the fixed and variable costs associated with camera  
trapping and line transects.

	Description	Camera traps		Line transects	
		Amount	Total Cost	Amount	Total Cost
514	Fixed costs	External hard drive	1	67.50	-
515		Camera traps, including import taxes	3	151.08	-
516		Storage cards	3	18.39	1 6.13
517		AA batteries	24	23.08	-
518		Photo camera to record animal sightings	-	-	1 770.52
519		Trail establishment	-	-	3 4522.61
520		Trail cleaning (only for monitoring)	-	-	3 2261.31
521		<b>Total</b>		<b>1129.83</b>	<b>21128.41</b>
522	Variable costs	Traveling to the field site	2	29.60	2 29.60
523		Food for two people	2	46.90	4 93.80
524		Lodging for two people	2	73.70	4 147.40
525		Per diem for field assistant	2	50.25	4 100.50
526		Per diem for researcher	2	402.01	4 804.02
527		Hours to screen photos	1.5	90.45	-
528		Car rental (days)	2	76.79	4 153.58
529		Fuel (liters)	34.54	41.66	44.54 53.72
530		<b>Total per sampling unit</b>		<b>2933.11</b>	<b>7649.09</b>



536 **Table 2** - List of species recorded by line transects and camera traps in this study, organized by  
 537 order and family.

538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 Classification	538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 Common name	538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 Line transect	538 539 540 541 542 543 544 545 546 547 548 549 550 551 552 553 554 555 556 557 558 559 560 561 562 563 564 565 566 567 568 569 570 571 572 573 574 575 576 577 578 579 580 581 Camera trap
<b>Pilosa</b>			
Myrmecophagidae			
<i>Myrmecophaga tridactyla</i>	Giant Anteater		x
<i>Tamandua tetradactyla</i>	Southern Tamandua	x	x
<b>Cingulata</b>			
Dasypodidae			
<i>Cabassous unicinctus</i>	Amazon Naked-tailed Armadillo		x
<i>Dasypus novemcinctus</i>	Nine-banded Armadillo		x
<i>Euphractus sexcinctus</i>	Yellow Armadillo		x
<i>Priodontes maximus</i>	Giant Armadillo		x
<b>Primates</b>			
Cebidae			
<i>Sapajus apella</i>	Black-capped Capuchin	x	x
<i>Saimiri ustus</i>	Golden-backed Squirrel Monkey	x	x
Pitheciidae			
<i>Chiropotes albinasus</i>	White-nosed Saki	x	
<i>Pithecia irrorata</i>	Gray's Bald-faced Saki	x	
<i>Plecturocebus parecis</i>	Parecis Titi	x	
Atelidae			
<i>Ateles chamek</i>	Black Spider Monkey	x	
<i>Lagothrix lagothricha</i>	Common Woolly Monkey	x	
Callitrichidae			
<i>Mico melanurus</i>	Black-tailed Marmoset		x
<b>Carnivora</b>			
Felidae			
<i>Leopardus pardalis</i>	Ocelot		x
<i>Panthera onca</i>	Jaguar		x
<i>Herpailurus yagouaroundi</i>	Jaguarundi		x
Canidae			
<i>Atelocynus microtis</i>	Short-eared Dog		x
<i>Cerdocyon thous</i>	Crab-eating Fox		x
<i>Speothos venaticus</i>	Bush Dog		x
Mustelidae			
<i>Eira barbara</i>	Tayra	x	x
Procyonidae			
<i>Nasua nasua</i>	South American Coati		x
<i>Procyon cancrivorus</i>	Crab-eating Raccoon		x
<b>Perissodactyla</b>			
Tapiridae			
<i>Tapirus terrestris</i>	Lowland Tapir	x	x
<b>Artiodactyla</b>			
Tayassuidae			

583	<i>Pecari tajacu</i>	Collared Peccary	x	x
584	<i>Tayassu pecari</i>	White-lipped Peccary	x	x
585	Cervidae			
586	<i>Mazama nemorivaga</i>	Amazonian Brown Brocket	x	x
587	<b>Rodentia</b>			
588	Sciuridae			
589	<i>Sciurus aestuans</i>	Brazilian Squirrel		x
590	Caviidae			
591	<i>Hydrochoerus hydrochaeris</i>	Capybara	x	x
592	Cuniculidae			
593	<i>Cuniculus paca</i>	Paca		x
594	Dasyproctidae			
595	<i>Dasyprocta azarae</i>	Agouti	x	x
596	Erethizontidae			
597	<i>Coendou prehensilis</i>	Brazilian Porcupine	x	

**FIGURE LEGENDS**

600 **Figure 1** - The study area's location, showing the transects (purple lines) and camera trap sites  
601 (yellow points) used to sample medium- and large-sized mammals in the Rondon II  
602 Hydroelectric Power Plant, Rondônia state, southern Brazilian Amazon. Sources: Google  
603 Satellite and IBGE.

604 **Figure 2** - Relationship between resulting diversity (inventory) or 1 - bias (monitoring) and  
605 sampling cost (in US\$) for three biodiversity dimensions (taxonomic, functional, and  
606 phylogenetic). Each point represents a combination of sampling units of camera traps and  
607 transects. Points representing the most cost-effective arrangements (i.e., optimal sampling  
608 designs) are highlighted in orange. Note that for taxonomic diversity inventory, defining an  
609 optimal sampling design is impossible, as diversity increases gradually with sampling cost.

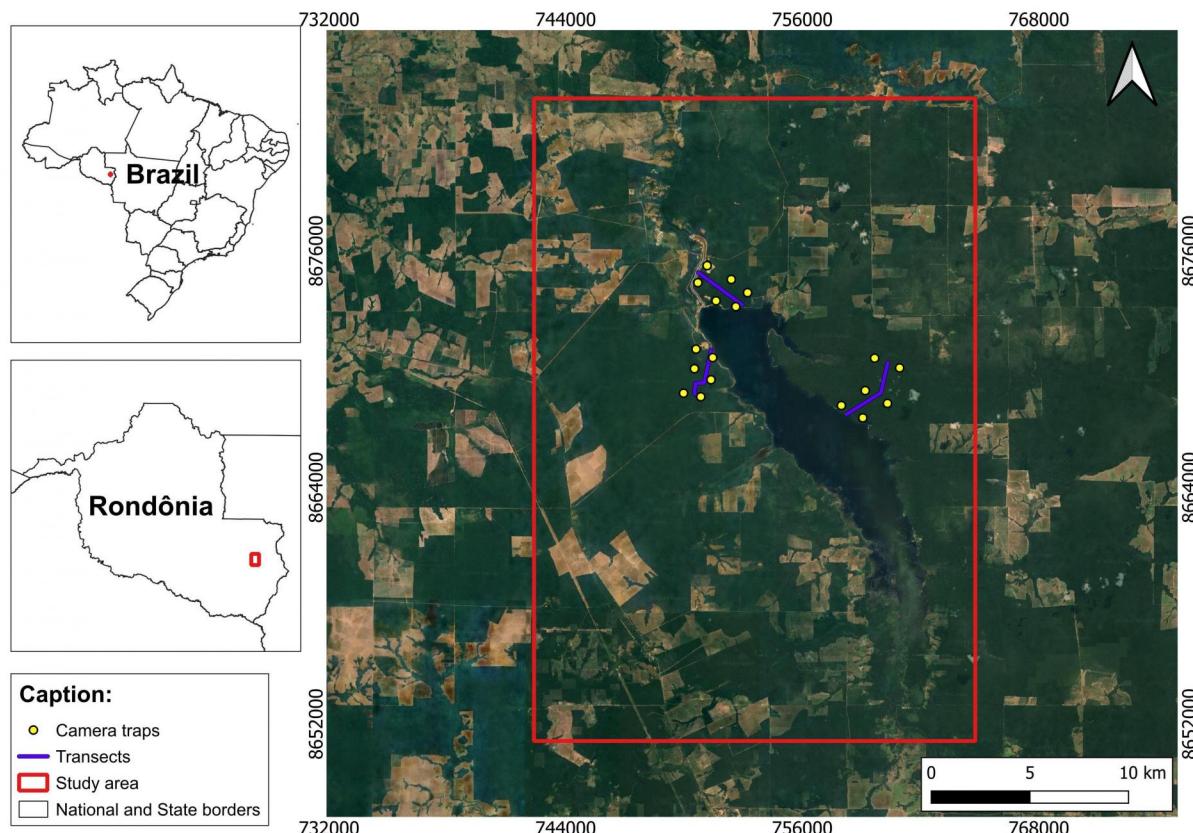


Figure 1 - The study area's location, showing the transects (purple lines) and camera trap sites (yellow points) used to sample medium- and large-sized mammals in the Rondon II Hydroelectric Power Plant, Rondônia state, southern Brazilian Amazon. Sources: Google Satellite and IBGE.

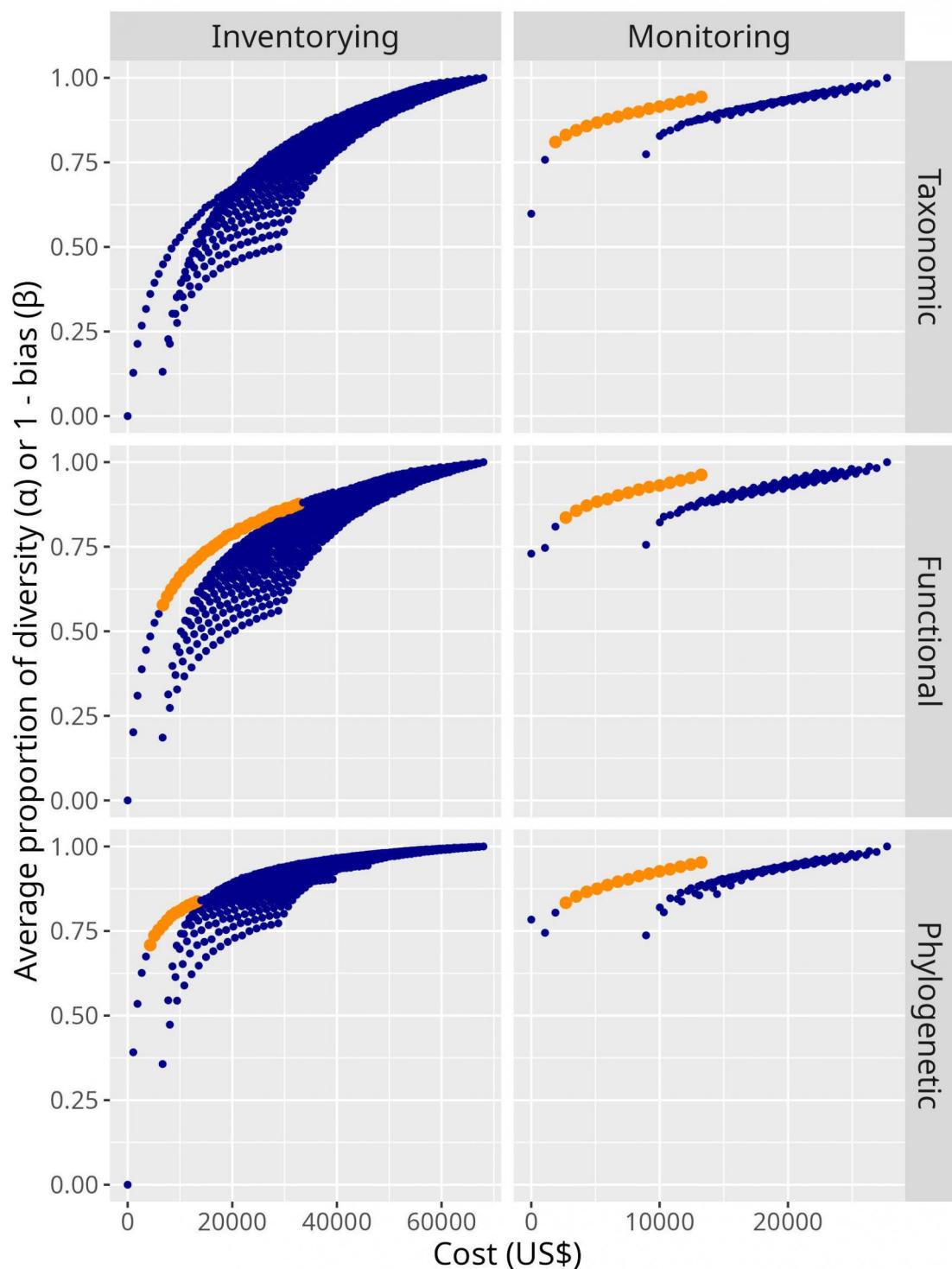
**Figure 2**[Download JPG \(733.49 kB\)](#)

Figure 2 - Relationship between resulting diversity (inventory) or 1 - bias (monitoring) and sampling cost (in US\$) for three biodiversity dimensions (taxonomic, functional, and phylogenetic). Each point represents a combination of sampling units of camera traps and transects. Points representing the most cost-effective arrangements (i.e., optimal sampling designs) are highlighted in orange. Note that for taxonomic diversity inventory, defining an optimal sampling design is impossible, as diversity increases gradually with sampling cost.

**Manuscript body**[Download source file \(579.27 kB\)](#)**Figures****Figure 1 -** [Download source file \(874.4 kB\)](#)

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